

Substitute for form 1449A/PTO

**INFORMATION DISCLOSURE
STATEMENT BY APPLICANT**

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Complete if Known

Sheet 1 of 3

Application Number 09/811,358
 Filing Date March 16, 2001
 First Named Inventor Gregory L. MERRILL
 Group Art Unit 3739
 Examiner Name John M. Mulcahy
 Attorney Docket Number IMMR-022/01US

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TECHNOLOGY CENTER R3700

U.S. PATENT DOCUMENTS

Examiner Initials*	Cite No. ¹	U.S. Patent Document		Name of Patentee or Applicant of Cited Document	Date of Publication of Cited Document MM-DD-YYYY
		Number	Kind Code ² (if known)		
jm	A1	5,785,630		Bobick, et al.	07/28/1998
	A2	5,766,016		Sinclair et al.	06/16/1998
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		Office ³	Number ⁴	Kind Code ⁵ (if known)			
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	B2						

¹ Unique citation designation number.² See attached Kinds of U.S. Patent Documents.³ Enter Office that issued the document, by the two-letter code (WIPO Standard ST.3).⁴ For Japanese patent documents, the indication of the year of the reign of the Emperor must precede the serial number of the patent document.⁵ Kind of document by the appropriate symbols as indicated on the document under WIPO Standard ST. 16 if possible.⁶ Applicant is to place a check mark here if English language Translation is attached.

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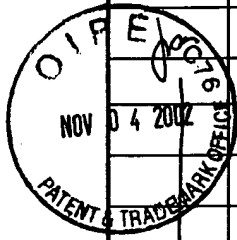
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Sheet	2	3	Application Number	09/811,358	 NOV - 5 2002 TECHNOLOGY CENTER F3700
			Filing Date	March 16, 2001	
			First Named Inventor	Gregory L. MERRILL	
			Group Art Unit	3739	
			Examiner Name	John M. Mulcahy	
			Attorney Docket Number	IMMR-022/01US	

OTHER PRIOR ART - NON PATENT LITERATURE DOCUMENTS

Examiner Initials*	Cite No. ¹	Include name of the author (in CAPITAL LETTERS), title of the article (when appropriate), title of the item (book, magazine, journal, serial, symposium, catalog, etc.), date, page(s), volume-issue number(s), publisher, city and/or country where published.	T ²
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	C2	Iwata, "Pen-based Haptic Virtual Environment," 0-7803-1363-1/93 IEEE, pp. 287-292, 1993	
	C3	Russo, "The Design and Implementation of a Three Degree of Freedom Force Output Joystick," <i>MIT Libraries Archives</i> pp. 1-131, May 1990, archived 8/14/90	
	C4	Brooks et al., "Hand Controllers for Teleoperation - A State-of-the-Art Technology Survey and Evaluation," <i>JPL Publication 85-11</i> , NASA-CR-175890; N85-28559, pp. 1-84, 03/1/1985	
	C5	Jones et al., "A perceptual analysis of stiffness," ISSN 0014-4819 Springer International (Springer-Verlag); <i>Experimental Brain Research</i> , Vol. 79, No. 1, pp. 150-156, 1990	
	C6	Burdea et al., "Distributed Virtual Force Feedback, Lecture Notes for Workshop on Force Display in Virtual Environments and its Application to Robotic Teleoperation," <i>1993 IEEE International Conference on Robotics and Automation</i> , pp. 25-44, 05/02/1993	
	C7	Snow et al., "Model-X Force-Reflecting-Hand-Controller," NT Control No. NPO-17851; JPL Case No. 7348, pp. 1-4 with 45 pages of attachments, 06/15/1989	
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	C9	Tadros, "Control System Design for a Three Degree of Freedom Virtual Environment Simulator Using Motor/Brake Pair Actuators," <i>MIT Archive</i> , pp. 1-88, February 1990, archived 8/13/90	
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	C11	Adelstein et al., "Design and Implementation of a Force Reflecting Manipulandum for Manual Control research," DSC-Vol. 42, <i>Advances in Robotics</i> , pp. 1-12, 1992	
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	C16	Patrick et al., "Design and Testing of A Non-reactive, Fingertip, Tactile Display for Interaction with Remote Environments," <i>Cooperative Intelligent Robotics in Space</i> , Rui J. deFigueiredo et al, Editor, Proc. SPIE Vol. 1387, pp. 215-222, 1990	
	C17	Adelstein, "A Virtual Environment System For The Study of Human Arm Tremor," <i>Ph.D. Dissertation</i> , Dept. of Mechanical Engineering, MIT, June 1989, archived 3/13/90	
	C18	Bejczy, "Sensors, Controls, and Man-Machine Interface for Advanced Teleoperation," <i>Science</i> , Vol. 208, No. 4450, pp. 1327-1335, 1980	
	C19	Bejczy et al., "Generalization of Bilateral Force-Reflecting Control of Manipulators," <i>Proceedings Of Fourth CISM-IFTOMM</i> , Sep. 8-12, 1981	
	C20	McAfee et al., "Teleoperator Subsystem/Telerobot Demonstrator: Force Reflecting Hand Controller Equipment Manual," <i>JPL 1988</i> , JPL D-5172	
	C21	Minsky, "Computational Haptics: The Sandpaper System for Synthesizing Texture for a Force-Feedback Display," <i>Ph.D. Dissertation</i> , MIT, June 1995, archived 7/6/95	
	C22	Jacobsen et al., "High Performance, Dexterous Telerobotic Manipulator With Force Reflection," <i>Intervention/ROV '91 Conference & Exposition</i> , Hollywood, Florida, May 21-23, 1991	
	C23	Shimoga, "Finger Force and Touch Feedback Issues in Dexterous Telemanipulation," <i>Proceedings of Fourth Annual Conference on Intelligent Robotic Systems for Space Exploration</i> , Rensselaer Polytechnic Institute, Sep. 30- Oct. 1, 1992	
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				Examiner Name	John M. Mulcahy
				Attorney Docket Number	IMMR-022/01US

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*EXAMINER: Initial if reference considered, whether or not citation is in conformance with MPEP 609. Draw line through citation if not in conformance and not considered. Include copy of this form with next communication to applicant.

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¹ Unique citation designation number.

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